

Determinants in K-theory and multivariable operator theory

Joseph Migler

University of Colorado

International Workshop on Operator Theory
Queen's University Belfast
4 September 2014

Table of Contents

- 1 The determinant invariant
 - Algebraic K -theory
 - Definitions
 - Examples
- 2 Joint torsion
 - Torsion
 - Definitions
 - Examples
- 3 Joint torsion equals the determinant invariant
 - Main results
 - Further work

Table of Contents

- 1 The determinant invariant
 - Algebraic K -theory
 - Definitions
 - Examples
- 2 Joint torsion
 - Torsion
 - Definitions
 - Examples
- 3 Joint torsion equals the determinant invariant
 - Main results
 - Further work

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor
- In general: Quillen defined $K_i(R)$

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor
- In general: Quillen defined $K_i(R) =$ R

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor
- In general: Quillen defined $K_i(R) = \quad GL(R)$

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor
- In general: Quillen defined $K_i(R) = BGL(R)$

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor
- In general: Quillen defined $K_i(R) = BGL(R)^+$

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor
- In general: Quillen defined $K_i(R) = BGL(R)^+ \times K_0(R)$

Atiyah: "K-theory may roughly be described as the study of additive (or abelian) invariants of large matrices."

Algebraic K -theory consists of functors that assign to each ring R and ideal I a collection of groups that fit into a long exact sequence

$$\cdots \rightarrow K_{i+1}(R/I) \rightarrow K_i(R, I) \rightarrow K_i(R) \rightarrow K_i(R/I) \rightarrow \cdots$$

- K -theory has its origin in Grothendieck's work on generalizing the Riemann-Roch Theorem.
- K_1 : Bass, Whitehead
- K_2 : Milnor
- In general: Quillen defined $K_i(R) = \pi_i(BGL(R)^+ \times K_0(R))$

Brown's determinant invariant

Now we specialize to the case when $R = \mathcal{B} = \mathcal{B}(H)$, bounded operators, and $I = \mathcal{L}^1 = \mathcal{L}^1(H)$, trace class operators.

Brown's determinant invariant

Now we specialize to the case when $R = \mathcal{B} = \mathcal{B}(H)$, bounded operators, and $I = \mathcal{L}^1 = \mathcal{L}^1(H)$, trace class operators.

- For any invertible commuting elements $a, b \in \mathcal{B}/\mathcal{L}^1$, there is a Steinberg symbol (Loday product, up to a sign)

$$\{a, b\} \in K_2(\mathcal{B}/\mathcal{L}^1)$$

Brown's determinant invariant

Now we specialize to the case when $R = \mathcal{B} = \mathcal{B}(H)$, bounded operators, and $I = \mathcal{L}^1 = \mathcal{L}^1(H)$, trace class operators.

- For any invertible commuting elements $a, b \in \mathcal{B}/\mathcal{L}^1$, there is a Steinberg symbol (Loday product, up to a sign)

$$\{a, b\} \in K_2(\mathcal{B}/\mathcal{L}^1)$$

- There is a boundary map

$$\partial : K_2(\mathcal{B}/\mathcal{L}^1) \rightarrow K_1(\mathcal{B}, \mathcal{L}^1)$$

Brown's determinant invariant

Now we specialize to the case when $R = \mathcal{B} = \mathcal{B}(H)$, bounded operators, and $I = \mathcal{L}^1 = \mathcal{L}^1(H)$, trace class operators.

- For any invertible commuting elements $a, b \in \mathcal{B}/\mathcal{L}^1$, there is a Steinberg symbol (Loday product, up to a sign)

$$\{a, b\} \in K_2(\mathcal{B}/\mathcal{L}^1)$$

- There is a boundary map

$$\partial : K_2(\mathcal{B}/\mathcal{L}^1) \rightarrow K_1(\mathcal{B}, \mathcal{L}^1)$$

- The Fredholm determinant induces a map

$$\det : K_1(\mathcal{B}, \mathcal{L}^1) \rightarrow \mathbf{C}^\times$$

Brown's determinant invariant

Now we specialize to the case when $R = \mathcal{B} = \mathcal{B}(H)$, bounded operators, and $I = \mathcal{L}^1 = \mathcal{L}^1(H)$, trace class operators.

- For any invertible commuting elements $a, b \in \mathcal{B}/\mathcal{L}^1$, there is a Steinberg symbol (Loday product, up to a sign)

$$\{a, b\} \in K_2(\mathcal{B}/\mathcal{L}^1)$$

- There is a boundary map

$$\partial : K_2(\mathcal{B}/\mathcal{L}^1) \rightarrow K_1(\mathcal{B}, \mathcal{L}^1)$$

- The Fredholm determinant induces a map

$$\det : K_1(\mathcal{B}, \mathcal{L}^1) \rightarrow \mathbf{C}^\times$$

Definition

Let $a, b \in \mathcal{B}/\mathcal{L}^1$ be invertible commuting elements. The **determinant invariant** $d(a, b) = \det \partial\{a, b\} \in \mathbf{C}^\times$.

Theorem (Brown, '75)

If a, b have invertible lifts $A, B \in \mathcal{L}$, respectively, then $\det(ABA^{-1}B^{-1}) = d(a, b)$.

Theorem (Brown, '75)

If a, b have invertible lifts $A, B \in \mathcal{L}$, respectively, then $\det(ABA^{-1}B^{-1}) = d(a, b)$.

- If $A = e^\alpha$ and $B = e^\beta$ for some operators α and β with $[\alpha, \beta] \in \mathcal{L}^1$, then the Helton-Howe-Pincus formula implies

$$d(a, b) = e^{\text{tr}[\alpha, \beta]}.$$

Theorem (Brown, '75)

If a, b have invertible lifts $A, B \in \mathcal{L}$, respectively, then $\det(ABA^{-1}B^{-1}) = d(a, b)$.

- If $A = e^\alpha$ and $B = e^\beta$ for some operators α and β with $[\alpha, \beta] \in \mathcal{L}^1$, then the Helton-Howe-Pincus formula implies

$$d(a, b) = e^{\text{tr}[\alpha, \beta]}.$$

- If f and g are smooth functions on the unit circle, then

$$d(T_{e^f} + \mathcal{L}^1, T_{e^g} + \mathcal{L}^1) = \exp \frac{1}{2\pi i} \int f dg.$$

Theorem (Brown, '75)

If a, b have invertible lifts $A, B \in \mathcal{L}$, respectively, then $\det(ABA^{-1}B^{-1}) = d(a, b)$.

- If $A = e^\alpha$ and $B = e^\beta$ for some operators α and β with $[\alpha, \beta] \in \mathcal{L}^1$, then the Helton-Howe-Pincus formula implies

$$d(a, b) = e^{\text{tr}[\alpha, \beta]}.$$

- If f and g are smooth functions on the unit circle, then

$$d(T_{e^f} + \mathcal{L}^1, T_{e^g} + \mathcal{L}^1) = \exp \frac{1}{2\pi i} \int f dg.$$

Theorem (Kaad, '11)

$d(a, b)$ is the Connes-Karoubi multiplicative character of $\{a, b\}$.

Table of Contents

- 1 The determinant invariant
 - Algebraic K -theory
 - Definitions
 - Examples
- 2 Joint torsion
 - Torsion
 - Definitions
 - Examples
- 3 Joint torsion equals the determinant invariant
 - Main results
 - Further work

Let (V_\bullet, d_\bullet) be an exact sequence of finite dimensional vector spaces:

$$0 \rightarrow V_n \xrightarrow{d_n} V_{n-1} \xrightarrow{d_{n-1}} V_{n-2} \rightarrow \cdots \rightarrow V_0 \rightarrow 0$$

Let (V_\bullet, d_\bullet) be an exact sequence of finite dimensional vector spaces:

$$0 \rightarrow V_n \xrightarrow{d_n} V_{n-1} \xrightarrow{d_{n-1}} V_{n-2} \rightarrow \cdots \rightarrow V_0 \rightarrow 0$$

Denote by $\det V_k$ the top exterior power $\Lambda^{\dim V_k} V_k$ and define

$$\det V_\bullet = \det V_n^* \otimes \det V_{n-1} \otimes \det V_{n-2}^* \otimes \cdots$$

Let (V_\bullet, d_\bullet) be an exact sequence of finite dimensional vector spaces:

$$0 \rightarrow V_n \xrightarrow{d_n} V_{n-1} \xrightarrow{d_{n-1}} V_{n-2} \rightarrow \cdots \rightarrow V_0 \rightarrow 0$$

Denote by $\det V_k$ the top exterior power $\Lambda^{\dim V_k} V_k$ and define

$$\det V_\bullet = \det V_n^* \otimes \det V_{n-1} \otimes \det V_{n-2}^* \otimes \cdots$$

Theorem (Knudsen-Mumford, '76)

*There is a canonical volume element $\tau(V_\bullet, d_\bullet) \in \det V_\bullet$, known as the **torsion** of (V_\bullet, d_\bullet) .*

Let (V_\bullet, d_\bullet) be an exact sequence of finite dimensional vector spaces:

$$0 \rightarrow V_n \xrightarrow{d_n} V_{n-1} \xrightarrow{d_{n-1}} V_{n-2} \rightarrow \cdots \rightarrow V_0 \rightarrow 0$$

Denote by $\det V_k$ the top exterior power $\Lambda^{\dim V_k} V_k$ and define

$$\det V_\bullet = \det V_n^* \otimes \det V_{n-1} \otimes \det V_{n-2}^* \otimes \cdots$$

Theorem (Knudsen-Mumford, '76)

*There is a canonical volume element $\tau(V_\bullet, d_\bullet) \in \det V_\bullet$, known as the **torsion** of (V_\bullet, d_\bullet) .*

(For each k , pick a nonzero element $t_k \in \Lambda^{\text{rank } d_k} V_k$ such that $d_k t_k \neq 0$. By exactness, $d_k t_k \wedge t_{k-1} \in \det V_{k-1}$ is nonzero. Then let

$$\tau(V_\bullet, d_\bullet) = (t_n)^* \otimes (d_n t_n \wedge t_{n-1}) \otimes (d_{n-1} t_{n-1} \wedge t_{n-2})^* \otimes \cdots$$

Joint torsion

Let A and B be commuting operators on a vector space H :

Joint torsion

Let A and B be commuting operators on a vector space H :

$$\begin{array}{ccc} H & \xrightarrow{A} & H \\ B \downarrow & & \downarrow B \\ H & \xrightarrow{A} & H \end{array}$$

Joint torsion

Let A and B be commuting operators on a vector space H :

$$\begin{array}{ccc} H & \xrightarrow{A} & H \\ B \downarrow & & \downarrow B \\ H & \xrightarrow{A} & H \end{array}$$

Then B can be regarded as a morphism of Koszul complexes:

$$B : K_{\bullet}(A) \rightarrow K_{\bullet}(A)$$

Joint torsion

Let A and B be commuting operators on a vector space H :

$$\begin{array}{ccc} H & \xrightarrow{A} & H \\ B \downarrow & & \downarrow B \\ H & \xrightarrow{A} & H \end{array}$$

Then B can be regarded as a morphism of Koszul complexes:

$$B : K_{\bullet}(A) \rightarrow K_{\bullet}(A)$$

The mapping cone construction defines an exact triangle

$$K_{\bullet}(A) \rightarrow K_{\bullet}(A) \rightarrow K_{\bullet}(A, B) \rightarrow$$

Joint torsion

Let A and B be commuting operators on a vector space H :

$$\begin{array}{ccc} H & \xrightarrow{A} & H \\ B \downarrow & & \downarrow B \\ H & \xrightarrow{A} & H \end{array}$$

Then B can be regarded as a morphism of Koszul complexes:

$$B : K_{\bullet}(A) \rightarrow K_{\bullet}(A)$$

The mapping cone construction defines an exact triangle

$$K_{\bullet}(A) \rightarrow K_{\bullet}(A) \rightarrow K_{\bullet}(A, B) \rightarrow$$

and hence a long exact sequence in homology:

$$\mathcal{E}_B : \cdots \rightarrow H_{i+1}(A, B) \rightarrow H_i(A) \rightarrow H_i(A) \rightarrow H_i(A, B) \rightarrow \cdots$$

Switching the roles of A and B , we obtain

$$\mathcal{E}_A : \cdots \rightarrow H_{i+1}(A, B) \rightarrow H_i(B) \rightarrow H_i(B) \rightarrow H_i(A, B) \rightarrow \cdots$$

Switching the roles of A and B , we obtain

$$\mathcal{E}_A : \cdots \rightarrow H_{i+1}(A, B) \rightarrow H_i(B) \rightarrow H_i(B) \rightarrow H_i(A, B) \rightarrow \cdots$$

If A and B are Fredholm then all homology spaces are finite dimensional, and hence we have torsion vectors

$$\tau(\mathcal{E}_A) \in \det H_\bullet(A, B) \quad \text{and} \quad \tau(\mathcal{E}_B) \in \det H_\bullet(A, B)$$

Switching the roles of A and B , we obtain

$$\mathcal{E}_A : \cdots \rightarrow H_{i+1}(A, B) \rightarrow H_i(B) \rightarrow H_i(B) \rightarrow H_i(A, B) \rightarrow \cdots$$

If A and B are Fredholm then all homology spaces are finite dimensional, and hence we have torsion vectors

$$\tau(\mathcal{E}_A) \in \det H_\bullet(A, B) \quad \text{and} \quad \tau(\mathcal{E}_B) \in \det H_\bullet(A, B)$$

Here we make use of the canonical isomorphism

$$\det V^* \otimes \det V \cong \mathbf{C}$$

Switching the roles of A and B , we obtain

$$\mathcal{E}_A : \cdots \rightarrow H_{i+1}(A, B) \rightarrow H_i(B) \rightarrow H_i(B) \rightarrow H_i(A, B) \rightarrow \cdots$$

If A and B are Fredholm then all homology spaces are finite dimensional, and hence we have torsion vectors

$$\tau(\mathcal{E}_A) \in \det H_\bullet(A, B) \quad \text{and} \quad \tau(\mathcal{E}_B) \in \det H_\bullet(A, B)$$

Here we make use of the canonical isomorphism

$$\det V^* \otimes \det V \cong \mathbf{C}$$

Definition

The **joint torsion** $\tau(A, B)$ of two Fredholm operators is (up to a sign) the nonzero scalar

$$\tau(A, B) = \tau(\mathcal{E}_A) \otimes \tau(\mathcal{E}_B)^*$$

Examples

- If A and B are commuting Fredholm operators with $H_i(A, B) = 0$ for $i = 0, 1, 2$, then

Examples

- If A and B are commuting Fredholm operators with $H_i(A, B) = 0$ for $i = 0, 1, 2$, then

$$\tau(A, B) = \frac{\det B|_{\ker A}}{\det B|_{\operatorname{coker} A}} \frac{\det A|_{\operatorname{coker} B}}{\det A|_{\ker B}}$$

Examples

- If A and B are commuting Fredholm operators with $H_i(A, B) = 0$ for $i = 0, 1, 2$, then

$$\tau(A, B) = \frac{\det B|_{\ker A}}{\det B|_{\operatorname{coker} A}} \frac{\det A|_{\operatorname{coker} B}}{\det A|_{\ker B}}$$

- In particular, if $B = \exp \beta$ for some β , then we recover the Lefschetz number:

Examples

- If A and B are commuting Fredholm operators with $H_i(A, B) = 0$ for $i = 0, 1, 2$, then

$$\tau(A, B) = \frac{\det B|_{\ker A}}{\det B|_{\operatorname{coker} A}} \frac{\det A|_{\operatorname{coker} B}}{\det A|_{\ker B}}$$

- In particular, if $B = \exp \beta$ for some β , then we recover the Lefschetz number:

$$\tau(A, e^\beta) = \exp \operatorname{tr} (\beta|_{\ker A} - \beta|_{\operatorname{coker} A}).$$

Examples

- If A and B are commuting Fredholm operators with $H_i(A, B) = 0$ for $i = 0, 1, 2$, then

$$\tau(A, B) = \frac{\det B|_{\ker A}}{\det B|_{\operatorname{coker} A}} \frac{\det A|_{\operatorname{coker} B}}{\det A|_{\ker B}}$$

- In particular, if $B = \exp \beta$ for some β , then we recover the Lefschetz number:

$$\tau(A, e^\beta) = \exp \operatorname{tr} (\beta|_{\ker A} - \beta|_{\operatorname{coker} A}).$$

- Setting $\beta = I$, we recover the index of A :

Examples

- If A and B are commuting Fredholm operators with $H_i(A, B) = 0$ for $i = 0, 1, 2$, then

$$\tau(A, B) = \frac{\det B|_{\ker A}}{\det B|_{\operatorname{coker} A}} \frac{\det A|_{\operatorname{coker} B}}{\det A|_{\ker B}}$$

- In particular, if $B = \exp \beta$ for some β , then we recover the Lefschetz number:

$$\tau(A, e^\beta) = \exp \operatorname{tr} (\beta|_{\ker A} - \beta|_{\operatorname{coker} A}).$$

- Setting $\beta = I$, we recover the index of A :

$$\log \tau(A, eI) = \operatorname{index} A.$$

Perturbation vectors

What if A and B do not commute, but $[A, B] \in \mathcal{L}^1$?

Perturbation vectors

What if A and B do not commute, but $[A, B] \in \mathcal{L}^1$?

Assume that there exist C and D such that

$$A - D, B - C \in \mathcal{L}^1 \quad \text{and} \quad AB = CD$$

Perturbation vectors

What if A and B do not commute, but $[A, B] \in \mathcal{L}^1$?

Assume that there exist C and D such that

$$A - D, B - C \in \mathcal{L}^1 \quad \text{and} \quad AB = CD$$

There is a canonical generator $\sigma_{A,D} \in \det H_\bullet(A) \otimes \det H_\bullet(D)^*$ known as a **perturbation vector**, and similarly, $\sigma_{B,C}$.

Perturbation vectors

What if A and B do not commute, but $[A, B] \in \mathcal{L}^1$?

Assume that there exist C and D such that

$$A - D, B - C \in \mathcal{L}^1 \quad \text{and} \quad AB = CD$$

There is a canonical generator $\sigma_{A,D} \in \det H_\bullet(A) \otimes \det H_\bullet(D)^*$ known as a **perturbation vector**, and similarly, $\sigma_{B,C}$.

Definition (Carey-Pincus, '99)

The **joint torsion** $\tau(A, B, C, D)$ is the nonzero scalar

$$\tau(A, B, C, D) = \tau(\mathcal{E}_{A,D}) \otimes \tau(\mathcal{E}_{B,C})^* \otimes \sigma_{A,D} \otimes \sigma_{B,C}$$

Perturbation vectors

What if A and B do not commute, but $[A, B] \in \mathcal{L}^1$?

Assume that there exist C and D such that

$$A - D, B - C \in \mathcal{L}^1 \quad \text{and} \quad AB = CD$$

There is a canonical generator $\sigma_{A,D} \in \det H_\bullet(A) \otimes \det H_\bullet(D)^*$ known as a **perturbation vector**, and similarly, $\sigma_{B,C}$.

Definition (Carey-Pincus, '99)

The **joint torsion** $\tau(A, B, C, D)$ is the nonzero scalar

$$\tau(A, B, C, D) = \tau(\mathcal{E}_{A,D}) \otimes \tau(\mathcal{E}_{B,C})^* \otimes \sigma_{A,D} \otimes \sigma_{B,C}$$

Joint torsion was used to investigate Szegő limit theorems on the asymptotics of determinants of Toeplitz matrices.

Perturbation vectors

What if A and B do not commute, but $[A, B] \in \mathcal{L}^1$?

Assume that there exist C and D such that

$$A - D, B - C \in \mathcal{L}^1 \quad \text{and} \quad AB = CD$$

There is a canonical generator $\sigma_{A,D} \in \det H_\bullet(A) \otimes \det H_\bullet(D)^*$ known as a **perturbation vector**, and similarly, $\sigma_{B,C}$.

Definition (Carey-Pincus, '99)

The **joint torsion** $\tau(A, B, C, D)$ is the nonzero scalar

$$\tau(A, B, C, D) = \tau(\mathcal{E}_{A,D}) \otimes \tau(\mathcal{E}_{B,C})^* \otimes \sigma_{A,D} \otimes \sigma_{B,C}$$

Joint torsion was used to investigate Szegő limit theorems on the asymptotics of determinants of Toeplitz matrices.

Conjecture

$$\tau(A, B, C, D) = d(a, b).$$

Table of Contents

- 1 The determinant invariant
 - Algebraic K -theory
 - Definitions
 - Examples
- 2 Joint torsion
 - Torsion
 - Definitions
 - Examples
- 3 Joint torsion equals the determinant invariant
 - Main results
 - Further work

Group actions

Let $\pi : \mathcal{B} \rightarrow \mathcal{B}/\mathcal{L}^1$. Denote by S_a the set of quadruples (A, B, C, D) of Fredholm operators such that $\pi(A) = a$ and

$$AB = CD, \quad A - D \in \mathcal{L}^1, \quad B - C \in \mathcal{L}^1$$

Group actions

Let $\pi : \mathcal{B} \rightarrow \mathcal{B}/\mathcal{L}^1$. Denote by S_a the set of quadruples (A, B, C, D) of Fredholm operators such that $\pi(A) = a$ and

$$AB = CD, \quad A - D \in \mathcal{L}^1, \quad B - C \in \mathcal{L}^1$$

Define the group G_a by

$$\{(U, V) \in GL(H)^2 \mid \pi(U) = \pi(V), [\pi(U), a] = 0\}$$

Group actions

Let $\pi : \mathcal{B} \rightarrow \mathcal{B}/\mathcal{L}^1$. Denote by S_a the set of quadruples (A, B, C, D) of Fredholm operators such that $\pi(A) = a$ and

$$AB = CD, \quad A - D \in \mathcal{L}^1, \quad B - C \in \mathcal{L}^1$$

Define the group G_a by

$$\{(U, V) \in GL(H)^2 \mid \pi(U) = \pi(V), [\pi(U), a] = 0\}$$

G_a acts on S_a on the right by

$$(A, B, C, D) \bullet (U, V) = (A, BU, CV, V^{-1}DU)$$

Group actions

Let $\pi : \mathcal{B} \rightarrow \mathcal{B}/\mathcal{L}^1$. Denote by S_a the set of quadruples (A, B, C, D) of Fredholm operators such that $\pi(A) = a$ and

$$AB = CD, \quad A - D \in \mathcal{L}^1, \quad B - C \in \mathcal{L}^1$$

Define the group G_a by

$$\{(U, V) \in GL(H)^2 \mid \pi(U) = \pi(V), [\pi(U), a] = 0\}$$

G_a acts on S_a on the right by

$$(A, B, C, D) \bullet (U, V) = (A, BU, CV, V^{-1}DU)$$

Theorem (JM '14)

$$\tau((U, V) \bullet (A, B, C, D)) = d(a, \pi(U)) \cdot \tau(A, B, C, D)$$

Theorem (Kaad, '12)

If A and B are commuting operators on a finite dimensional vector space, then

$$\tau(A, B, B, A) = 1.$$

Theorem (Kaad, '12)

If A and B are commuting operators on a finite dimensional vector space, then

$$\tau(A, B, B, A) = 1.$$

The same result holds in the non-commutative setting, and also in infinite dimensions modulo trace class:

Theorem (Kaad, '12)

If A and B are commuting operators on a finite dimensional vector space, then

$$\tau(A, B, B, A) = 1.$$

The same result holds in the non-commutative setting, and also in infinite dimensions modulo trace class:

Theorem (JM '14)

If $A, B, C, D \in I + \mathcal{L}^1$, then

$$\tau(A, B, C, D) = 1.$$

Theorem (Kaad, '12)

If A and B are commuting operators on a finite dimensional vector space, then

$$\tau(A, B, B, A) = 1.$$

The same result holds in the non-commutative setting, and also in infinite dimensions modulo trace class:

Theorem (JM '14)

If $A, B, C, D \in I + \mathcal{L}^1$, then

$$\tau(A, B, C, D) = 1.$$

By combining this result with the previous slide, the following theorem, that joint torsion equals the determinant invariant, follows quickly.

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

- The joint torsion $\tau(A, B, C, D)$ does not depend on choice of C and D , and in fact only depends on the images $a = \pi(A)$ and $b = \pi(B)$ modulo \mathcal{L}^1 .

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

- The joint torsion $\tau(A, B, C, D)$ does not depend on choice of C and D , and in fact only depends on the images $a = \pi(A)$ and $b = \pi(B)$ modulo \mathcal{L}^1 .
- Hence we are justified in writing

$$\tau(a, b) = \tau(A, B, C, D)$$

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

- The joint torsion $\tau(A, B, C, D)$ does not depend on choice of C and D , and in fact only depends on the images $a = \pi(A)$ and $b = \pi(B)$ modulo \mathcal{L}^1 .
- Hence we are justified in writing

$$\tau(a, b) = \tau(A, B, C, D)$$

- $\tau(a, b)$ satisfies the usual Steinberg relations, i.e. skew-symmetry, bimultiplicativity, etc.

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

- $\tau(a_\lambda, b_\lambda)$ is continuous whenever the map $\lambda \mapsto (A_\lambda, B_\lambda)$ is continuous into the space of almost commuting pairs

$$\{(A, B) \mid A \text{ and } B \text{ are Fredholm and } [A, B] \in \mathcal{L}^1\}$$

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

- $\tau(a_\lambda, b_\lambda)$ is continuous whenever the map $\lambda \mapsto (A_\lambda, B_\lambda)$ is continuous into the space of almost commuting pairs

$$\{(A, B) \mid A \text{ and } B \text{ are Fredholm and } [A, B] \in \mathcal{L}^1\}$$

endowed with the metric

$$d((A_1, B_1), (A_2, B_2)) = \|A_1 - A_2\| + \|B_1 - B_2\| \\ + \|[A_1, B_1] - [A_2, B_2]\|_1$$

Theorem (JM '14)

Joint torsion equals the determinant invariant, that is,

$$\tau(A, B, C, D) = d(a, b)$$

Consequences:

- $\tau(a_\lambda, b_\lambda)$ is continuous whenever the map $\lambda \mapsto (A_\lambda, B_\lambda)$ is continuous into the space of almost commuting pairs

$$\{(A, B) \mid A \text{ and } B \text{ are Fredholm and } [A, B] \in \mathcal{L}^1\}$$

endowed with the metric

$$\begin{aligned} d((A_1, B_1), (A_2, B_2)) &= \|A_1 - A_2\| + \|B_1 - B_2\| \\ &\quad + \|[A_1, B_1] - [A_2, B_2]\|_1 \end{aligned}$$

- $d(a, b)$ can be computed in terms of finite dimensional data.

Theorem (Eschmeier-Putinar, '96)

Suppose A is a Fredholm n -tuple, $g \in \mathcal{O}(Sp(A))^n$, and $g(A)$ is Fredholm. Then

$$\text{ind } g(A) = \sum_{\{\lambda \in Sp(A) \mid g(\lambda) = 0\}} \text{deg}_\lambda(g) \cdot \text{ind}(A - \lambda)$$

Theorem (Eschmeier-Putinar, '96)

Suppose A is a Fredholm n -tuple, $g \in \mathcal{O}(Sp(A))^n$, and $g(A)$ is Fredholm. Then

$$\text{ind } g(A) = \sum_{\{\lambda \in Sp(A) \mid g(\lambda) = 0\}} \text{deg}_\lambda(g) \cdot \text{ind}(A - \lambda)$$

An analysis of determinants under the functional calculus yields results for Toeplitz operators:

Theorem (Eschmeier-Putinar, '96)

Suppose A is a Fredholm n -tuple, $g \in \mathcal{O}(Sp(A))^n$, and $g(A)$ is Fredholm. Then

$$\text{ind } g(A) = \sum_{\{\lambda \in Sp(A) \mid g(\lambda)=0\}} \text{deg}_\lambda(g) \cdot \text{ind}(A - \lambda)$$

An analysis of determinants under the functional calculus yields results for Toeplitz operators:

- If $f, g \in C^\infty(S^1)$ then $\tau(T_f, T_g)$ is given by

$$\exp \frac{1}{2\pi i} \left(\int \log f \, d(\log g) - \log g(p) \int d(\log f) \right)$$

Theorem (Eschmeier-Putinar, '96)

Suppose A is a Fredholm n -tuple, $g \in \mathcal{O}(\text{Sp}(A))^n$, and $g(A)$ is Fredholm. Then

$$\text{ind } g(A) = \sum_{\{\lambda \in \text{Sp}(A) \mid g(\lambda)=0\}} \text{deg}_\lambda(g) \cdot \text{ind}(A - \lambda)$$

An analysis of determinants under the functional calculus yields results for Toeplitz operators:

- If $f, g \in C^\infty(S^1)$ then $\tau(T_f, T_g)$ is given by

$$\exp \frac{1}{2\pi i} \left(\int \log f \, d(\log g) - \log g(p) \int d(\log f) \right)$$

- If $f, g \in H^\infty$, denote by $c_\lambda(f, g)$ the tame symbol of f and g .

$$\tau(T_f, T_g) = \prod_{|\lambda|<1} c_\lambda(f, g)$$

- Joint torsion of n -tuples for $n > 2$
 - ▶ Kaad, '12: commuting case
 - ▶ JM '13: perturbation vectors
 - ▶ Kaad-Nest '14: analyticity, localized torsion, tame symbols
 - ▶ Interpretation in higher algebraic K -theory

- Joint torsion of n -tuples for $n > 2$
 - ▶ Kaad, '12: commuting case
 - ▶ JM '13: perturbation vectors
 - ▶ Kaad-Nest '14: analyticity, localized torsion, tame symbols
 - ▶ Interpretation in higher algebraic K -theory
- The existence of suitable perturbations
 - ▶ $n = 2$: If $[A, B] \in \mathcal{L}^1$, when do there exist trace class perturbations C and D of A and B , respectively, such that $AB = CD$?
 - ▶ Brown-Douglas-Fillmore theory
 - ▶ $n > 2$

- Joint torsion of n -tuples for $n > 2$
 - ▶ Kaad, '12: commuting case
 - ▶ JM '13: perturbation vectors
 - ▶ Kaad-Nest '14: analyticity, localized torsion, tame symbols
 - ▶ Interpretation in higher algebraic K -theory
- The existence of suitable perturbations
 - ▶ $n = 2$: If $[A, B] \in \mathcal{L}^1$, when do there exist trace class perturbations C and D of A and B , respectively, such that $AB = CD$?
 - ▶ Brown-Douglas-Fillmore theory
 - ▶ $n > 2$
- Geometric examples: Toeplitz operators, pseudodifferential operators...

Thank you
very much